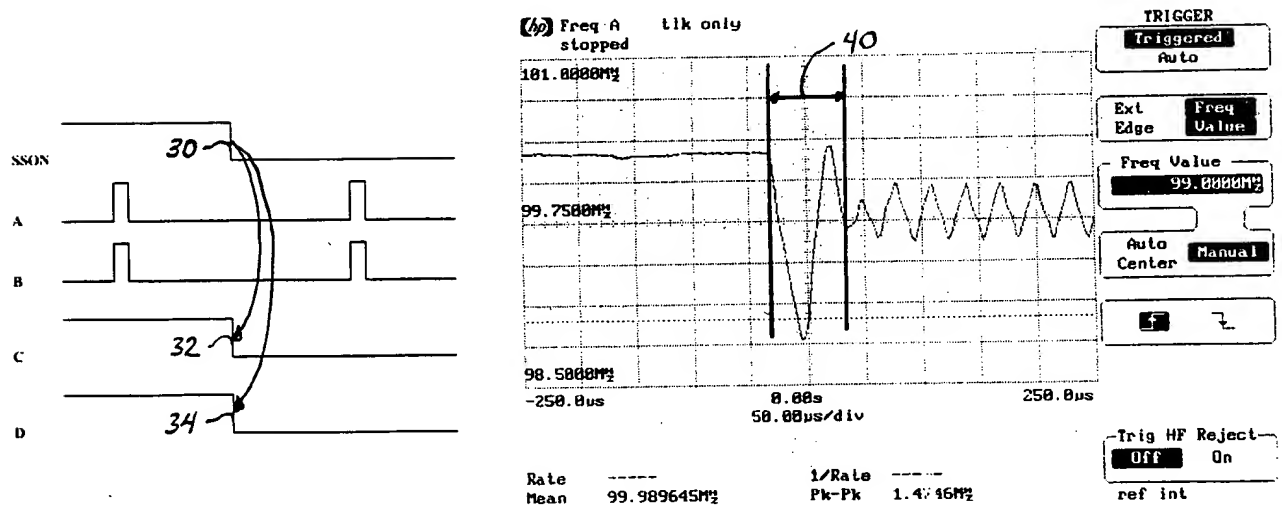


FIG.1



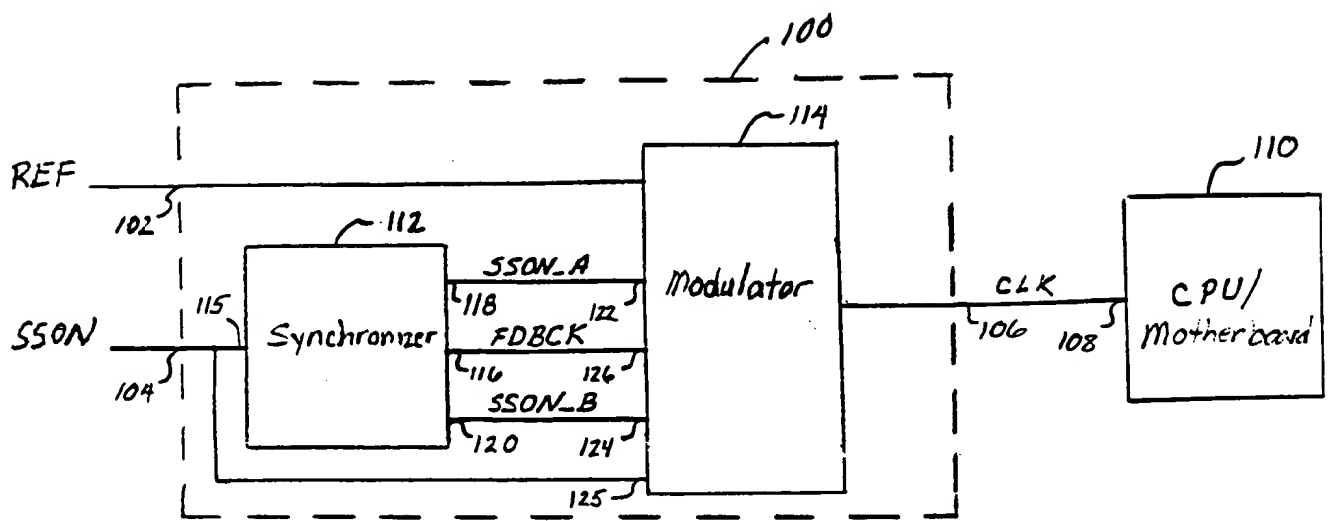


FIG.3

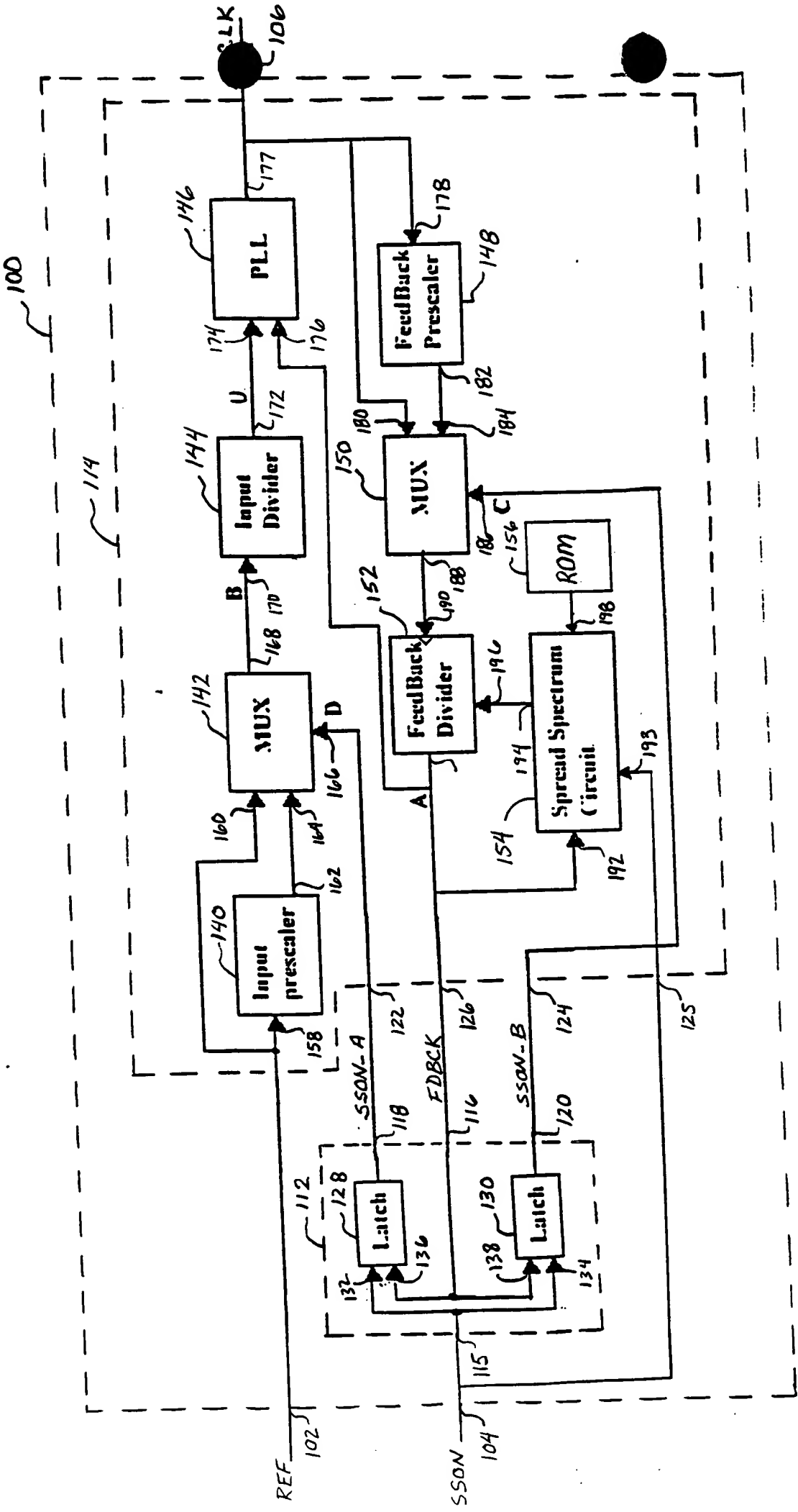


FIG.4

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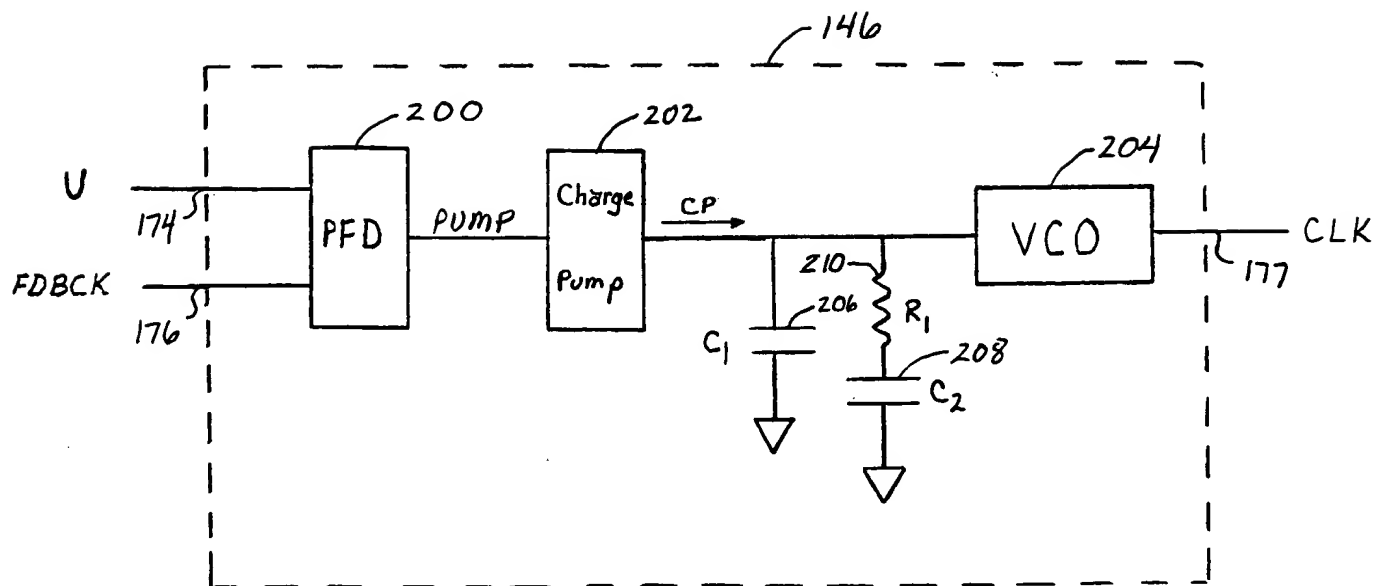
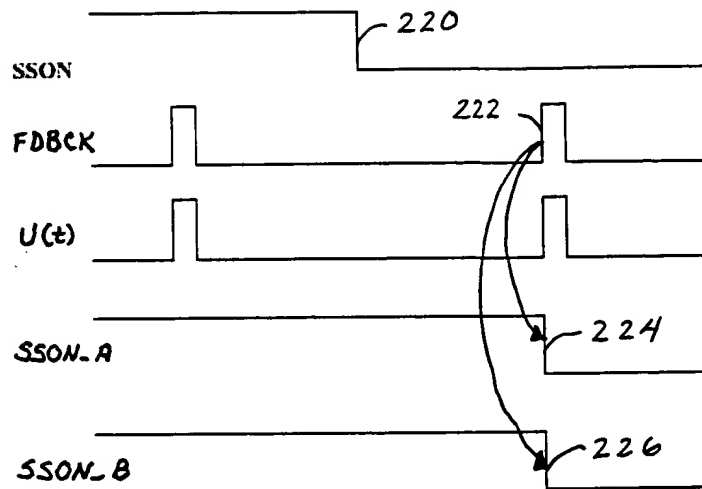
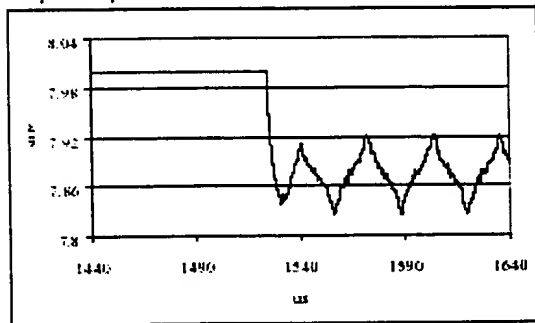


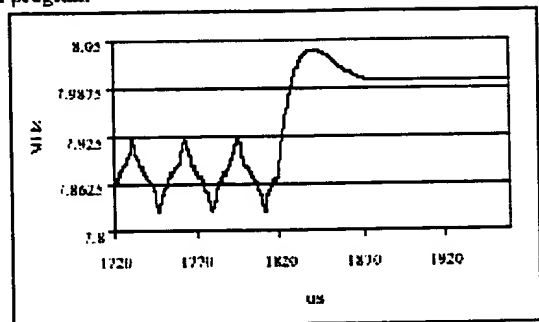
FIG.5



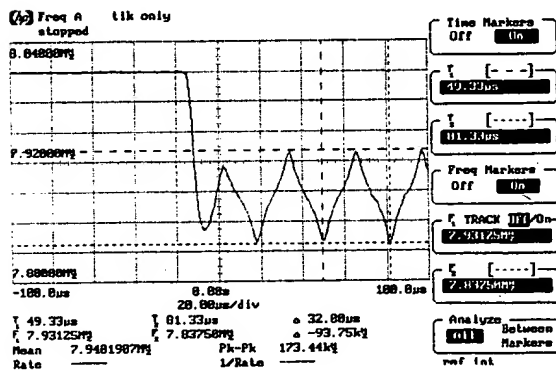
Spread Spectrum transition behaviors are controlled by the program



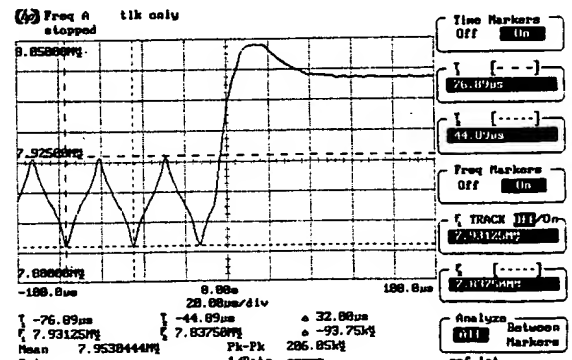
(a)



(a)



(b)



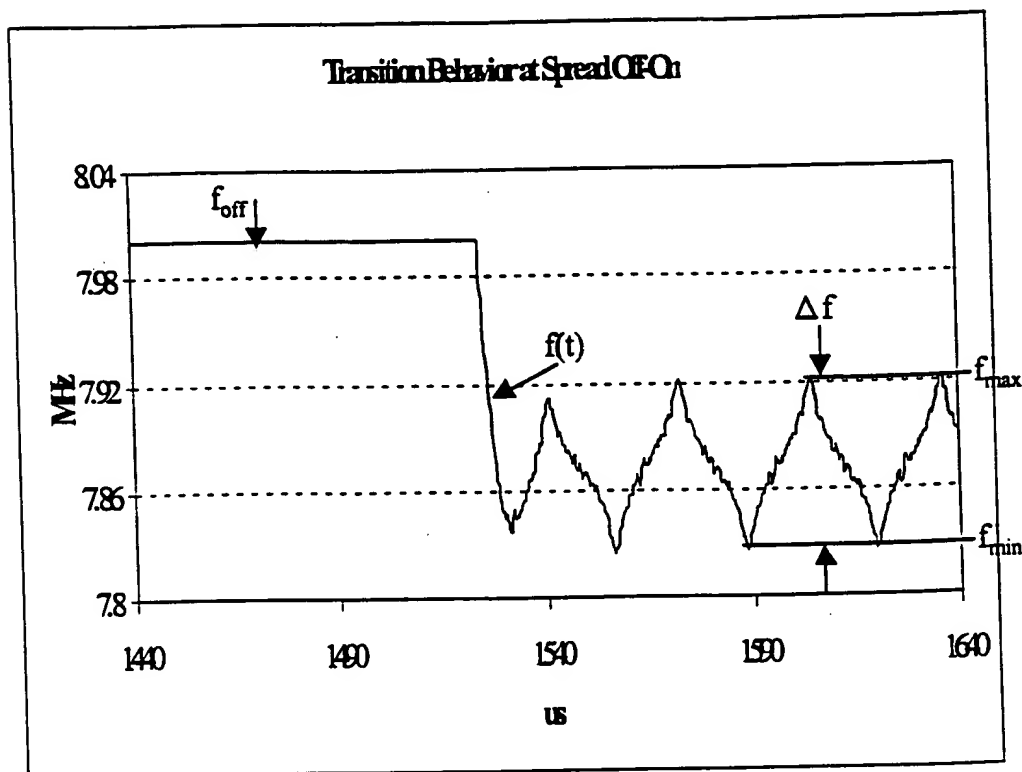
(b)

(a) Simulation (b) Measured results in off-on transition

(a) Simulation (b) Measured results in on-off transition

FIG. 6

Criteria for determining "good and bad" SS transient behavior



$f(t)$: PLL's running frequency in transient period

f_{off} : PLL's SSCG off frequency

f_{max} : Maximum frequency in SSCG on

f_{min} : Minimum frequency in SSCG on

Δf : Peak to peak frequency in SSCG

Criteria need to be satisfied:

Frequency running range during transient $f_{min} \leq f(t) \leq f_{off}$

FIG.7

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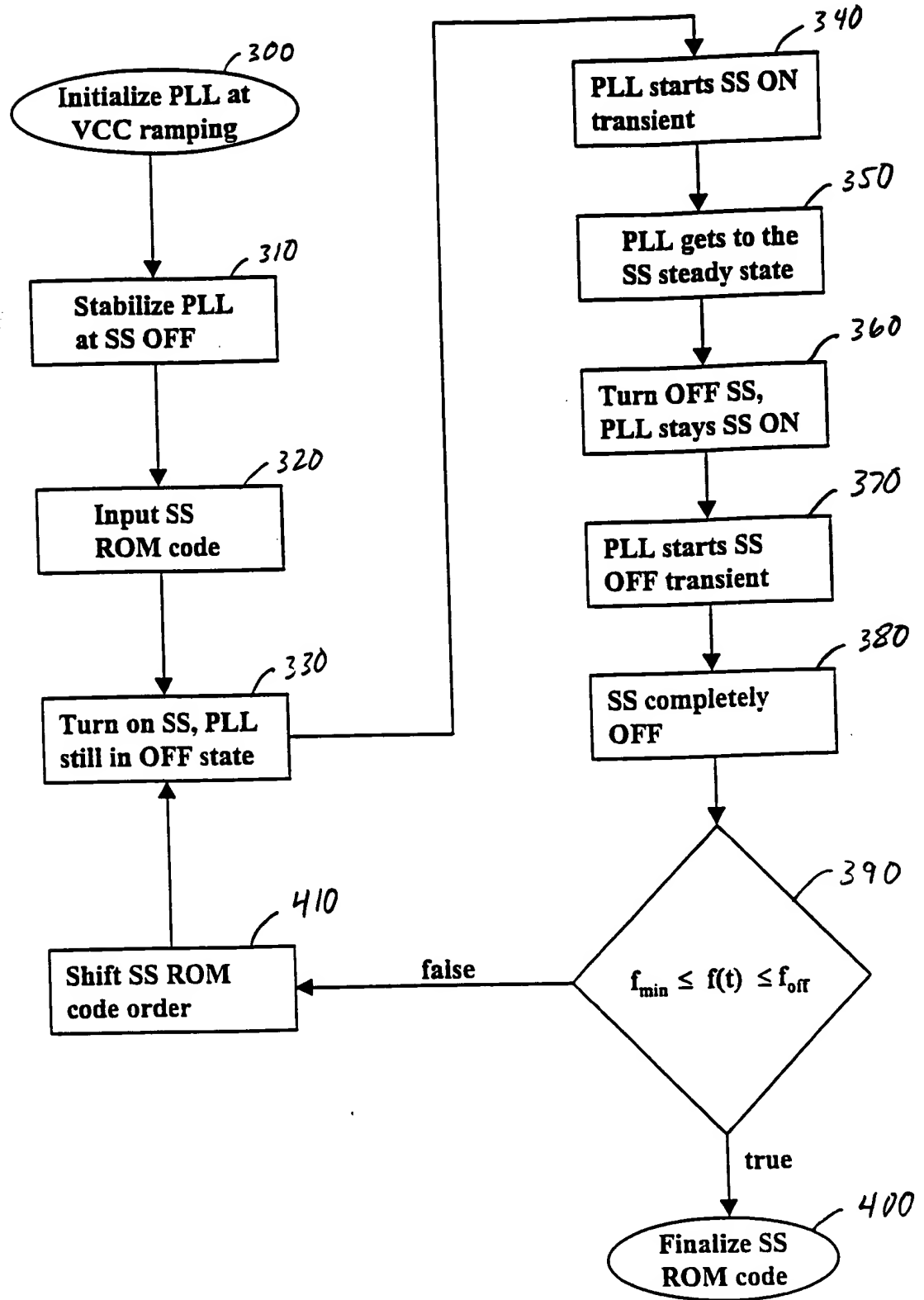
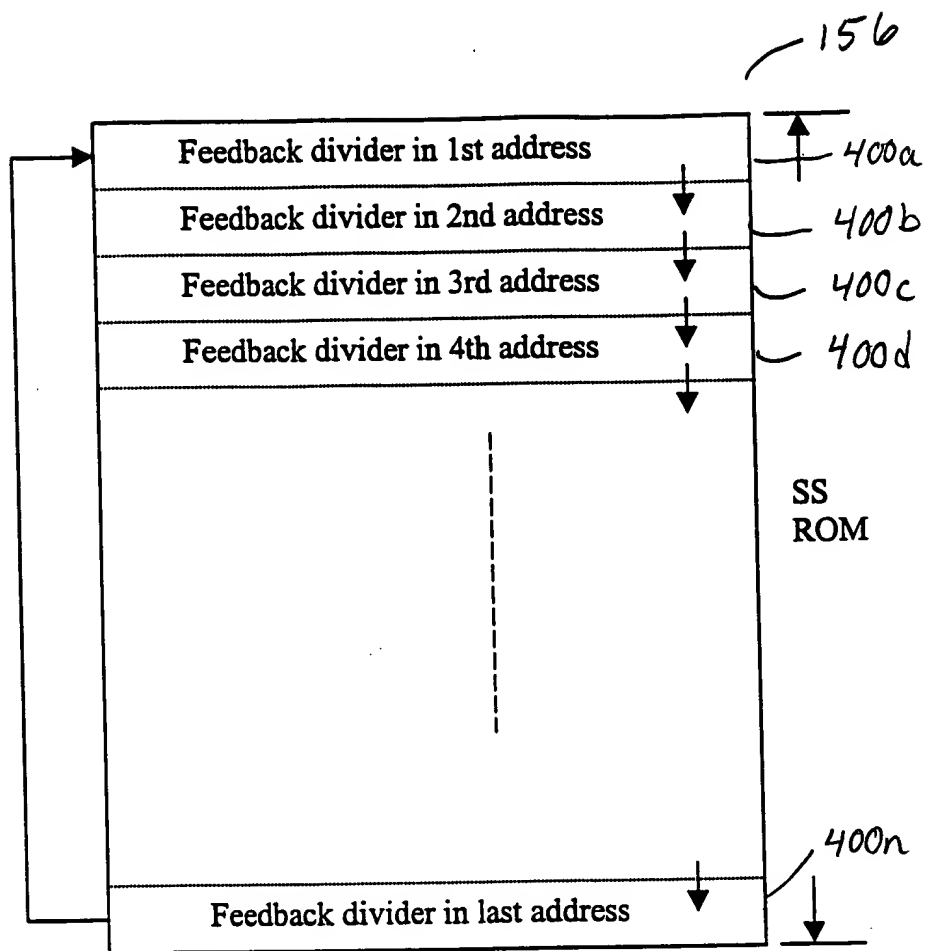


FIG.8

Order shifting step in response to bad behavior



Move feedback divider in last address to 1st address and shift down SS ROM code.

FIG.9